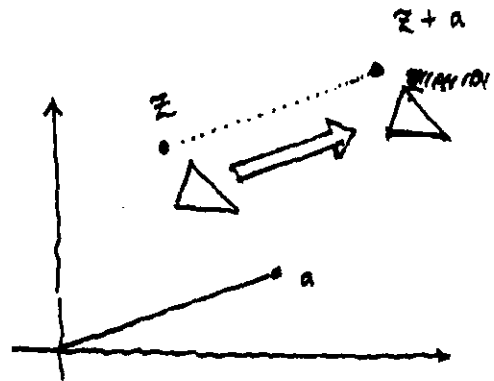


## §11. Euclidean transformations :

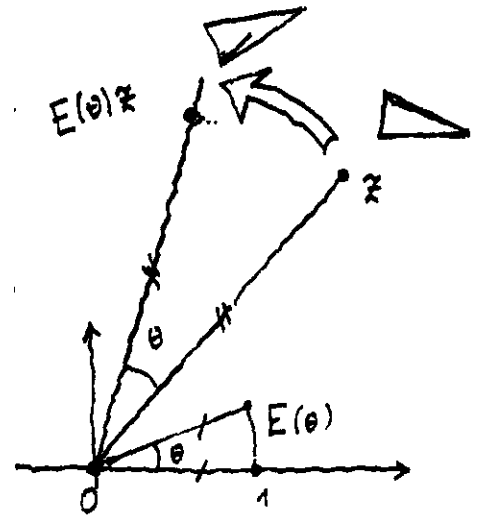
Addition of a fixed complex number results in a "translation" :

$$z \longrightarrow z + a$$



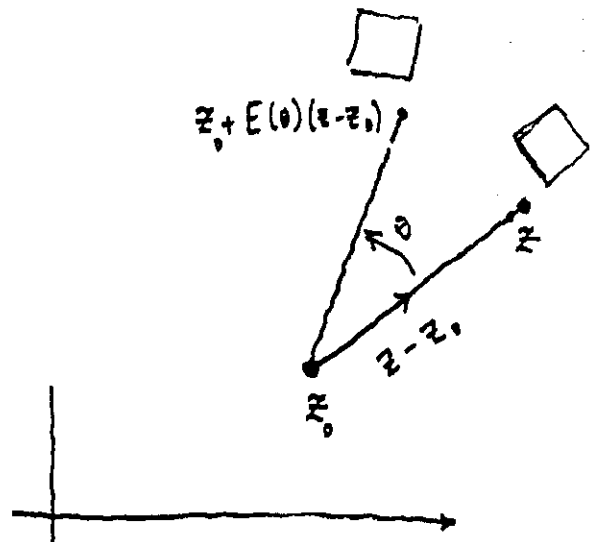
Multiplication by  $E(\theta)$  results in a rotation about  $0 \in \mathbb{C}$  through angle  $\theta$ .

$$z \longrightarrow E(\theta)z$$



Rotation about  $z_0 \in \mathbb{C}$  through angle  $\theta$

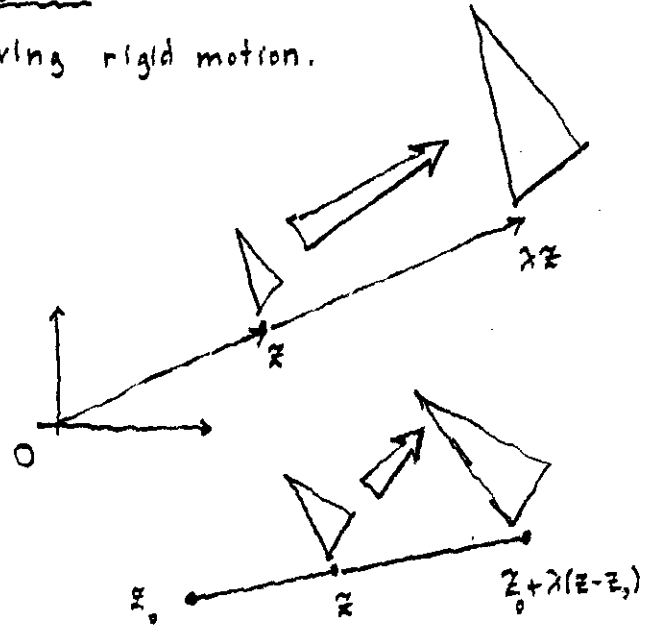
$$z \longrightarrow z_0 + E(\theta)(z - z_0)$$



A ~~any~~ composition of translation of translations and rotations is called a (n orientation preserving) rigid motion. Two geometric objects are called (directly) congruent if the one results from the other by an orientation preserving rigid motion.

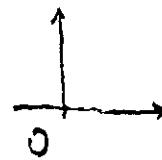
Multiplication by  $\lambda \in \mathbb{R} - \{0\}$  is a dilation about ~~the origin~~  $0 \in \mathbb{C}$  by factor  $\lambda$ :

$$z \rightarrow \lambda z$$



Dilation about  $z_0 \in \mathbb{C}$  by factor  $\lambda \in \mathbb{R} - \{0\}$ :

$$z \rightarrow z_0 + \lambda(z - z_0)$$



A composition of (o.p.) rigid motions and dilations is called a (n orientation preserving) similarity transformation. Two geometric objects are called (directly) similar if the one is obtained from the other by an <sup>o.p.</sup> similarity transformation.

PROBLEMS (4)

1. Prove that triangles with vertices  $a, b, c$  and  $a', b', c'$  are (directly) similar iff

$$\det \begin{bmatrix} 1 & 1 & 1 \\ a & b & c \\ a' & b' & c' \end{bmatrix} = 0 .$$

2. (a) Prove that  $a, b, c \in \mathbb{C}$  constitute the vertices of an equilateral triangle iff

$$\det \begin{bmatrix} 1 & 1 & 1 \\ a & b & c \\ b & c & a \end{bmatrix} = 0 .$$

(b) Prove that the roots of the equation

$$z^3 + Az^2 + Bz + C = 0$$

constitute the vertices of an equilateral triangle iff  $A^2 = 3B$ .

(c) Prove that  $0, a, b \in \mathbb{C}$  constitute the vertices of an equilateral triangle iff  $|a|^2 = |b|^2 = 2\operatorname{Re}(a\bar{b})$ .

## § 12. Topology of $\mathbb{C}$ :

The distance function  $d(z, w) = \text{dist}(z, w) = |z - w|$  is easily seen to satisfy the axioms for a metric function. The topology of  $\mathbb{C}$  is the metric topology induced by  $d$ . As such  $\mathbb{C}$  is indistinguishable from  $\mathbb{R}^2$ . So we freely discourse about limits, continuity <sup>and</sup> about sets that are open, closed, bounded, compact, connected <sub>the concepts of</sub> and boundary, closure, interior.

### Important Facts :

1. A continuous real valued function is bounded and attains its least upper & greatest lower bounds. / from above & below
2. A continuous real valued function with a connected domain, that takes negative and positive values attains 0.

## PROBLEMS (5)

1. In each of the following cases decide if the set of complex numbers  $z$  which satisfy the given relation is open closed, bounded, compact, connected :

(a)  $|z - i| \leq 1$

(b)  $|z - 2| > |z - 1|$

(c)  $\left| \frac{z - 1}{z + 1} \right| = 1$

(d)  $|z^2 - 1| < 1$

(e)  $|z^2| = \text{Im}(z)$

(f)  $\text{Re}\left(\frac{z}{1+i}\right) = 0$

(g)  $\text{Re}((1-i)\bar{z}) = 0$

§ 13. The fundamental theorem of algebra :

Theorem : Every non-constant polynomial with complex coefficients has a root in  $\mathbb{C}$ .

Proof : (Elementary proof due to E. Landau) <sup>≈ 1910.</sup> Consider  $\overset{\text{non-constant}}{p(X)} \in \mathbb{C}[X]$

1°  $p(z) \rightarrow \infty$  as  $z \rightarrow \infty$ .  $\therefore \exists z_0 \in \mathbb{C}$  such that  
 $\inf_{z \in \mathbb{C}} |p(z)| = |p(z_0)| \neq 0 > 0$

2° Assume w.l.o.g. that  $z_0 = 0$  : Replace, if necessary,  $p(z)$  by  $p(z + z_0)$ .

3° Assume w.l.o.g. that  $p(0) = 1$  : Replace, if necessary  $p(z)$  by  $(p(0))^{-1} p(z)$

$\therefore$  For some  $m \geq 1$   
4°  $p(z) = 1 + a_m z^m + a_{m+1} z^{m+1} + \dots + a_n z^n$

and we may assume <sup>w.l.o.g.</sup> that  $a_m = -1$  : Replace, if necessary  $p(z)$  by  $p(\omega z)$  where  $\omega^m = -1/a_m$ .

5° For  $t \in [0, 1]$

$$|p(t)| = \left| 1 - t^m + \sum_{k=m+1}^n a_k t^k \right| \leq 1 - t^m + \left( \sum_{k=m+1}^n |a_k| \right) t^{m+1}$$

But :  $\text{RHS} < 1$  if  $t < \left( \sum_{k=m+1}^n |a_k| \right)^{-1}$ .

§ 14. History :

1° Since long it ~~was~~ <sup>is</sup> known that some quadratic equations are not ~~long~~ "solvable" over  $\mathbb{R}$ . In the early 16. century the expression "not solvable" started to be replaced by "quadratic with imaginary roots".  
 quadratic

2° The use of imaginary quantities grew in importance as identities like

$$4 = \sqrt[3]{2 + 11\sqrt{-1}} + \sqrt[3]{2 - 11\sqrt{-1}}$$

(Rafael Bombelli ~ 1560)

started to occur more frequently, in late 16th century. The above particular identity results when one solves  $x^3 - 15x - 4 = 0$  the method of Cardano and notes that 4 is a root.

3° Leonhardt Euler introduces notation "i". Notices that  $E(\theta)$  is  $e^{i\theta}$ , formally by writing (1777)

$$\begin{aligned} e^{i\theta} &= 1 + i\theta + \frac{1}{2!} (i\theta)^2 + \frac{1}{3!} (i\theta)^3 + \dots \\ &= \underbrace{\left(1 - \frac{1}{2!} \theta^2 + \frac{1}{4!} \theta^4 - \dots\right)}_{\cos\theta} + i \underbrace{\left(\theta - \frac{1}{3!} \theta^3 + \frac{1}{5!} \theta^5 - \dots\right)}_{\sin\theta} \end{aligned}$$

4° <sup>The</sup> Interpretation of  $\mathbb{C}$  as a model of the Euclidean plane is due to Caspar Wessel <sup>Danish</sup> (1799)

Rediscovered by Jean-Robert Argand in 1806

by Carl Friedrich Gauss in 1831

5° C.F. Gauss introduces the terminology "Komplexe Zahl"  
~ 1830

6° Abstract definition of complex numbers as ordered pairs of real numbers:

William Rowan Hamilton in 1837

& higher dimensional analogues of  $\mathbb{C}$ :

"Classical number systems"

$\mathbb{N} \subseteq \mathbb{Z} \subseteq \mathbb{Q} \subseteq \mathbb{R} \subseteq \mathbb{C} \subseteq \mathbb{H} \subseteq \mathbb{O}$

— dim = 2 — dim = 4 — dim = 8  
"quaternions", Hamilton 1843  
"octonions"

John T. Graves 1843

Arthur Cayley 1850

7° Georg Friedrich Bernhard Riemann:

the "Riemann Sphere" ~ 1860.