

HOMEWORK 6

1. Consider manifolds M, N and $h : M \longrightarrow N$ which is submersive, in the sense that

$$T_m h : T_m M \longrightarrow T_{f(m)} N$$

is surjective for every $m \in M$.

(A) If $\omega \in \Omega^p(N)$ vanishes at no point in $h(M) \subseteq N$, prove that $h_*\omega \in \Omega^p(M)$ is nowhere vanishing.

(B) If M is not orientable, show that every $\lambda \in \Omega^r(N)$ vanishes at some point in $h(M) \subseteq N$, where $r = \dim N$.

2. The purpose of this problem is to present a diffeomorphism between $\mathbb{R}P^2$ and

$$SO(\mathbb{R}^3) = \{A \in \mathbb{R}^{3 \times 3} \mid A^T A = I, \det(A) = 1\}$$

that arises naturally from certain properties of quaternions. Let \mathbb{H} stand for the division ring of quaternions. Remember that for any $\mathbf{q} = a + bi + cj + dk \in \mathbb{H}$

$$\operatorname{Re}(\mathbf{q}) = a.$$

$\mathbf{q} \in \mathbb{H}$ is said to be **purely imaginary** if $\operatorname{Re}(\mathbf{q}) = 0$. If $\mathbf{q} \neq 0$, then

$$\mathbf{q}^{-1} = \frac{a - bi - cj - dk}{a^2 + b^2 + c^2 + d^2}.$$

(A) Remember that real numbers commute with quaternions. Prove that conjugation by quaternions send purely imaginary quaternions into purely imaginary quaternions. More precisely, prove that

$$\mathbf{q}i\mathbf{q}^{-1} = (a^2 + b^2 - c^2 - d^2)i + 2(bc + da)j + 2(bd - ca)k$$

for $\mathbf{q} = a + bi + cj + dk$. Similar expressions can be obtained for $\mathbf{q}j\mathbf{q}^{-1}$ and $\mathbf{q}k\mathbf{q}^{-1}$.

(B) Prove that $\operatorname{Re}(\mathbf{q}\mathbf{x}\mathbf{q}^{-1}) = \operatorname{Re}(\mathbf{x})$ for any $\mathbf{q}, \mathbf{x} \in \mathbb{H}$.

(C) Let $\langle \bullet, \bullet \rangle$ be the inner product on \mathbb{H} as vector space over \mathbb{R} , which arises from the natural identification of \mathbb{H} and \mathbb{R}^4 as vector spaces over \mathbb{R} . Prove that

$$\langle \mathbf{x}, \mathbf{y} \rangle = \operatorname{Re}(\mathbf{x}\bar{\mathbf{y}})$$

for any $\mathbf{x}, \mathbf{y} \in \mathbb{H}$.

(D) Prove that conjugation by quaternions is an isometry in \mathbb{H} . More precisely, show that

$$\langle \mathbf{q}\mathbf{x}\mathbf{q}^{-1}, \mathbf{q}\mathbf{y}\mathbf{q}^{-1} \rangle = \langle \mathbf{x}, \mathbf{y} \rangle$$

for any $\mathbf{q}, \mathbf{x}, \mathbf{y} \in \mathbb{H}$.

(E) Now it is a relatively simple task to check that the map $F : \mathbb{R}P^3 \longrightarrow SO(3)$ defined by

$$F([a, b, c, d]) = (a^2 + b^2 + c^2 + d^2)^{-1} \begin{bmatrix} a^2 + b^2 - c^2 - d^2 & 2(cb - da) & 2(db + ca) \\ 2(bc + da) & a^2 - b^2 + c^2 - d^2 & 2(dc - ba) \\ 2(bd - ca) & 2(cd + ba) & a^2 - b^2 - c^2 + d^2 \end{bmatrix}$$

is a diffeomorphism.